**University of Diyala College of Engineering** 

Engineering Mechanics Statics & Dynamics

First Glass Dep. Of Electrical power Eng.

Lecturer

M.S. Sultan N. Al-Gaisi 2016-2017

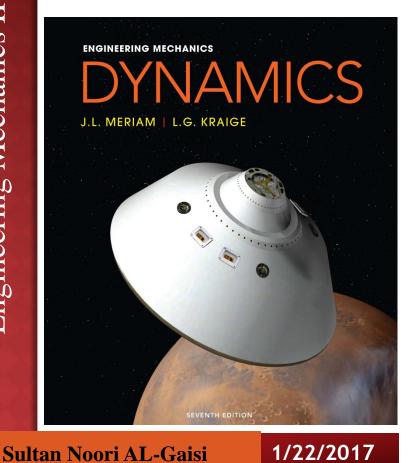
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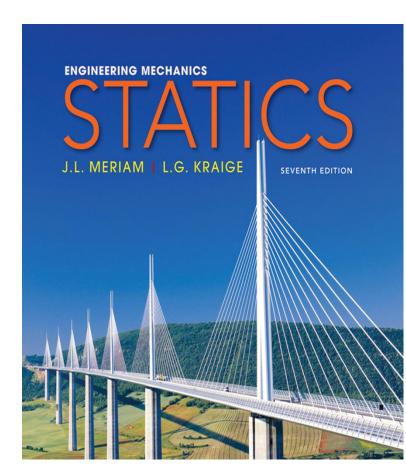
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Engineering Mechanics Statics and Dynamics

### \* Text Book

# Engineering mechanics Statics & Dynamics. 6<sup>th</sup>. (2010). J. L. <u>MERIAM</u> L. G. KRAIGE





#### Other books of Engineering Mechanics

- 1. Engineering mechanics statics & dynamics. 3th. Archie higdon.
- 2. Vector mechanics for engineering Ferdinand P. peer. 7<sup>th</sup>
- 3. Vector mechanics for engineering Ferdinand L. singer. 2th
- 4. Introduction of mechanics of solids. Egor. P. popov.
- 5. Engineering mechanics statics 12<sup>th</sup>. R. C. Hibbeler.

1/22/2017

Theory and Problems of Engineering mechanics statics & dynamics.
5<sup>th</sup> Scaum's outhine.



#### 4

### **Preface**

- Engineering mechanics is both a foundation and a framework for most of the branches of engineering.
- Engineering mechanics based upon the subjects of statics and dynamics.
- Even in a discipline such as electrical engineering, and inter in the electrical components of a robotic device or a manufacturing process.
- to solidify the student's understanding of other important subjects, including applied mathematics, physics, and graphics.

### primary purpose of Engineering Mechanics

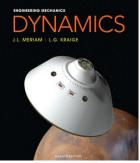
- to develop the capacity to predict the effects of force and motion.
- This capacity requires more than a mere knowledge of the physical and mathematical principles of mechanics.
- Also required is the ability to visualize physical configurations in terms of real materials, actual constraints, and the practical limitations which govern the behavior of machines and structures



### Categories of Mechanics:

- The subject of mechanics is logically divided into two parts:
- *statics*, which concerns the equilibrium of bodies under action of forces, and
- > *dynamics*, which concerns the motion of bodies.

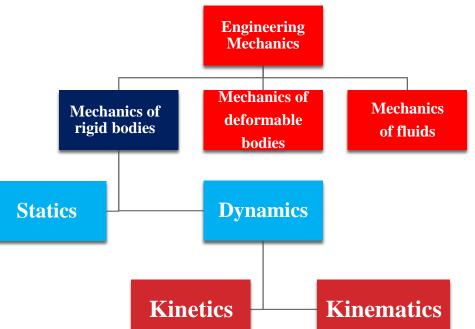
*Engineering Mechanics* is divided into these two parts, *Vol. 1 Statics. Vol. 2 Dynamics.* 





### <u>Statics</u>

- Force system
- Equilibrium
- Friction
- Centroids & center of gravity centroids



### <u>Dynamics</u>

- Kinetics of practical
- Rectilinear motion, curvilinear motion,.....
- *Kinetics: force, mass, and acceleration,.....*
- *Kinetics of practical Newton's* 2<sup>th</sup> *law*

### **\* Fundamental Concepts**

<u>Space</u> - associated with the notion of the position of a point P given in terms of three coordinates measured from a reference point or origin.

- <u>*Time*</u> definition of an event requires specification of the time and position at which it occurred.
- <u>Mass</u> used to characterize and compare bodies, e.g., response to earth's gravitational attraction and resistance to changes in translational motion.
- <u>*Force*</u> represents the action of one body on another. A force is characterized by its point of application, magnitude, and direction, i.e., a force is a vector quantity.

In Newtonian Mechanics, space, time, and mass are absolute concepts, independent of each other. Force, however, is not independent of the other three. The force acting on a body is related to the mass of the body and the variation of its velocity with time.

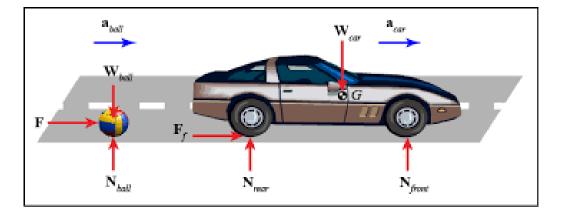
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### **\* Fundamental Concepts**

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A *particle* is a body of negligible dimensions. In the mathematical sense, a particle is a body whose dimensions are considered to be near zero so that we may analyze it as a mass concentrated at a point.

*Rigid body.* A body is considered rigid when the change in distance between any two of its points is negligible for the purpose at hand.



### Units

	DIMENSIONAL		SI UNI'	гs	U.S.	CUSTOM	ARY UNITS
QUANTITY	SYMBOL	U	NIT	SYMBOL	U	NIT	SYMBOL
Mass	М	١	kilogram	kg		slug	-
Length	$\mathbf{L}$	Base {	meter*	m	Base	∫ foot	$\mathbf{ft}$
Time	$\mathbf{T}$	units	second	S	units ·	second	sec
Force	$\mathbf{F}$		newton	Ν		pound	lb

10

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SI UNITS	U.S. CUSTOMARY UNITS
$(1 \text{ N}) = (1 \text{ kg})(1 \text{ m/s}^2)$ $N = \text{kg} \cdot \text{m/s}^2$	$\begin{array}{l} (1 \ lb) = (1 \ slug)(1 \ ft/sec^2) \\ slug = lb \cdot sec^2/ft \end{array}$

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### Units

TABLE 1-2	Conversion Factors	<b>i</b>	
Quantity	Unit of Measurement (FPS)	Equals	Unit of Measurement (SI)
Force	lb		4.448 N
Mass	slug		14.59 kg
Length	ft	0.304 8 m	

1/22/2017



11



Ex: Determine the weight in newton's of a car whose mass is 1400 kg. Convert the mass of the car to slugs and then determine its weight in pounds.

12

m = 1400 kg

$$W = mg = 1400(9.81) = 13\ 730\ N$$

$$m = 1400 \text{ kg} \left[ \frac{1 \text{ slug}}{14.594 \text{ kg}} \right] = 95.9 \text{ slugs}$$

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$$W = mg = (95.9)(32.2) = 3090$$
 lb

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## 13

### **\*** Fundamental principles

### **Newton's Laws**

•*Newton's First Law*: If the resultant force on a particle is zero, the particle will remain at rest or continue to move in a straight line.

•*Newton's Second Law*: A particle will have an acceleration proportional to a nonzero resultant applied force.



•*Newton's Law of Gravitation*: Two particles are attracted with equal and opposite forces,

$$F = G \frac{Mm}{r^2}$$
  $W = mg$ ,  $g = \frac{GM}{R^2}$ 

•*Newton's Third Law*: The forces of action and reaction between two particles have the same magnitude and line of action with opposite sense.

### **\* Scalars and Vectors**

We use two kinds of quantities in mechanics—scalars and vectors.

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*Scalar quantities* are those with which only a magnitude is associated. Examples of scalar quantities are time, volume, density, speed, energy, and mass.

*Vector quantities.* It's a quantity having magnitude and direction and which conforms to the parallogram of triangle laws. Examples of vector quantities are displacement, velocity, acceleration, force, moment, and momentum.

> Speed is a scalar. It is the magnitude of velocity, which is a vector. Thus velocity is specified by a direction as well as a speed.

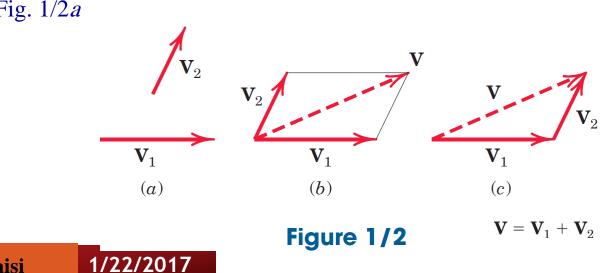
### **\*** *Vector quantities.*

The direction of the vector V may be measured by an angle from some known reference direction as shown in Fig. 1/1.

15

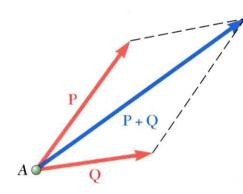
Figure 1/1

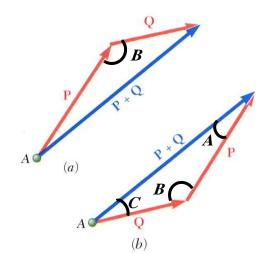
 Vectors must obey the <u>parallelogram law</u> of combination. This law states that two vectors V1 and V2, treated as free vectors, Fig. 1/2*a*



16

#### \* Addition of Vectors





• Law of cosines,

$$R^{2} = P^{2} + Q^{2} - 2PQ\cos B$$
$$\vec{R} = \vec{P} + \vec{Q}$$

• Law of sines,

$$\frac{\sin A}{Q} = \frac{\sin B}{R} = \frac{\sin C}{p}$$

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17

For the vectors  $\mathbf{V}_1$  and  $\mathbf{V}_2$  shown in the figure,

- (a) determine the magnitude S of their vector sum  $\mathbf{S} = \mathbf{V}_1 + \mathbf{V}_2$
- (b) determine the angle  $\alpha$  between **S** and the positive x-axis

**Solution** (a) We construct to scale the parallelogram shown in Fig. a for adding  $V_1$  and  $V_2$ . Using the law of cosines, we have

$$S^2 = 3^2 + 4^2 - 2(3)(4) \cos 105^\circ$$

S = 5.59 units

(b) Using the law of sines for the lower triangle, we have

$$\frac{\sin 105^{\circ}}{5.59} = \frac{\sin(\alpha + 30^{\circ})}{4}$$
$$\sin(\alpha + 30^{\circ}) = 0.692$$
$$(\alpha + 30^{\circ}) = 43.8^{\circ} \qquad \alpha = 13.76^{\circ}$$

 $V_1 = 4$  units  $45^{\circ}$  $30^{\circ}$  $V_2 = 3$  units  $V_1 = 4$  units 450 600  $45^{\circ}$ 30° 1059

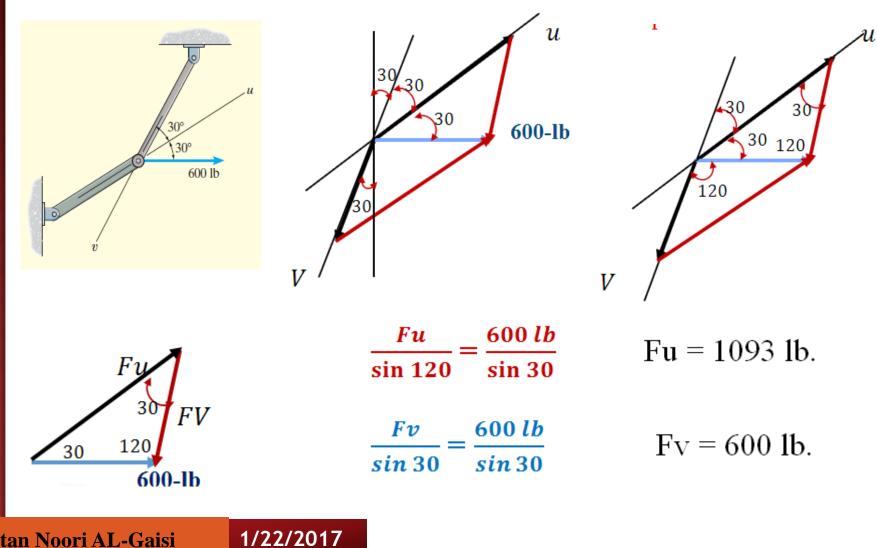
 $V_2 = 3$  units

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Ex :- Resolve the horizontal **600-lb** force in Fig. into components acting along the *u* and *v* axes and determine the magnitudes of these components.

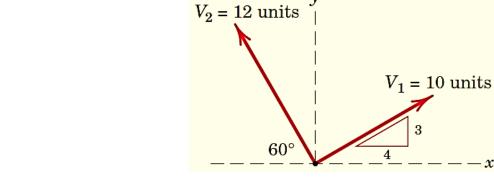
18



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### <u>H.w</u>

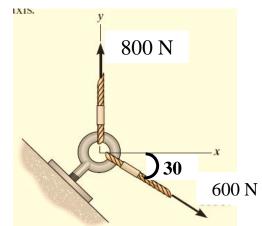
Q1/ Determine the magnitude of the vector sum  $v = v_1 + v_2$  and the angle  $\theta_x$  which v makes with the positive *x*-axis. Complete both graphical and algebraic solutions.



Q2/What is the mass in both slugs and kilograms of a 3000-lb car?

Q3/ Determine the magnitude of the resultant force and its direction measured counterclockwise from the positive x axis.

1/22/2017



19

Q4:- The guy cables AB and AC are attached to the top of the transmission tower. The tension in cable AC is 8 kN. Determine the required tension T in cable AB such that the net effect of the two cable tensions is a downward force at point A. Determine the magnitude R of this downward force.

